# A Note on the Myers and Read Capital Allocation Formula 

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#### Abstract

The Myers and Read capital allocation formula is an important new actuarial result. In this paper, we give an overview of the Myers and Read result, explain its significance to actuaries, and provide a simple proof. Then we explain the assumption the allocation formula makes on the underlying families of loss distributions as expected losses by line vary. We show that this assumption does not hold when insurers grow by writing more risks from a discrete group of insureds-as is typically the case. Next, we show that this failure has a material impact on the predicted results in a realistically sized portfolio of property casualty risks. This failure will severely limit the practical application of the Myers and Read allocation formula.


Keywords
G - Financial Economics; G220 - Insurance; Insurance Companies; G320 -
Financing Policy; Capital and Ownership Structure.

## 1 Introduction

In an important paper for actuaries, Myers and Read (2001) showed how to allocate the expected policy holder deficit in a multi-line insurance company uniquely to each line. Their work can also be used to allocate surplus to each line. Previous work on the allocation problem, including Phillips et al. (1998) and Merton and Perold (2001), had concluded that such an allocation could be inappropriate and misleading. The Myers and Read result is, therefore, a potentially significant breakthrough of great importance to actuaries.

Myers and Read repeatedly stress their result is independent of the distribution of losses by line and of any correlations between lines that may exist. They say their "proof requires no assumptions about the joint probability distributions of line-by-line losses and returns on the firm's portfolio of assets." However, while their result makes no assumptions about the static distribution of losses with fixed expected loss by line, their derivation does make an important assumption about how the dynamic distribution of losses changes shape as expected losses by line change. This paper will explain the significance of the latter assumption. We will show in Proposition 1 that it is a necessary and sufficient condition for the Myers and Read result to hold. Most importantly, we will show that the assumption does not hold when insurers grow through the assumption of risk from discrete insureds-as they do in the real world. Finally we will show, through three examples extending those in the original paper, that the predicted adds-up result materially fails to hold at the scale where it would be applied in practice.

For the convenience of readers not familiar with Myers and Read's work, we begin with an overview. Consider a simple insurance company which writes two lines of business. The losses from each line are represented by random variables $L_{1}$ and $L_{2}$, with means $l_{1}$ and $l_{2}$. Since the company can choose to write more or less of each line, we assume that the families $L_{1}\left(l_{1}\right)$ and $L_{2}\left(l_{2}\right)$ with varying means $l_{1}$ and $l_{2}$ are specified. For example, losses from line 1 may be normally distributed with mean $l_{1}$ and standard deviation 1000 and for line 2 be normally distributed with mean $l_{2}$ and coefficient of variation $\nu$. Assume the company has capital $k=s_{1} l_{1}+s_{2} l_{2}$ for constants $s_{1}$ and $s_{2}$, and total assets $l_{1}+l_{2}+k$. Let $s=k /\left(l_{1}+l_{2}\right)$ be the average capital ratio. Also assume that interest rates are zero. (Myers and Read show how to convert from deterministic investment income to stochastic income. We focus on deterministic income and set it equal to zero for simplicity. Nothing of substance is lost in doing so.) Let

$$
D_{M}\left(l_{1}, l_{2}\right)=\iint_{x_{1}+x_{2}>(1+s)\left(l_{1}+l_{2}\right)}\left(x_{1}+x_{2}-\left((1+s)\left(l_{1}+l_{2}\right)\right)\right) f\left(x_{1}, x_{2}\right) d x_{1} d x_{2}
$$

be the expected default with respect to the joint probability density $f$ of $L_{1}\left(l_{1}\right)$, and $L_{2}\left(l_{2}\right)$. It does not matter if the density $f$ is objective, when $D$ determines the expected values, or risk adjusted, when $D_{M}$ determines prices. Then, under certain assumptions on the distributions of the families $L_{1}\left(l_{1}\right)$ and $L_{2}\left(l_{2}\right)$ for varying $l_{1}, l_{2}$, but under no assumptions on the distributions of losses given fixed $l_{1}$ and $l_{2}$ Myers and Read prove

$$
\begin{equation*}
l_{1} \frac{\partial D_{M}}{\partial l_{1}}+l_{2} \frac{\partial D_{M}}{\partial l_{2}}=D_{M} \tag{1}
\end{equation*}
$$

This is obviously a very useful result: it gives a canonical allocation of the default value for the whole company to individual lines of business. It can be used to allocate surplus, and correctly allocate the cost of surplus to individual lines or business units.

## 2 Notation

We are modeling a multi-line insurance company. Losses from each line are modeled by random variables $L_{i}, i=1, \ldots, n$, where $L_{i}$ has mean $l_{i}$ and distribution function $F_{i}$. We will use the notation $F_{i}\left(x ; l_{i}\right)=\operatorname{Pr}\left(L_{i}\left(l_{i}\right)<x\right)$ when necessary to avoid any ambiguity. We often regard $l_{i}$ as a variable (but not a random variable), so each $L_{i}$ is really a family of distributions indexed by $l_{i}$. Where necessary we emphasize this by writing $L_{i}\left(l_{i}\right)$. Changes in $l_{i}$ correspond to increasing or decreasing volume in line $i$, since $l_{i}$ is the a priori expected loss. These changes can come about by assuming risks from more insureds, which is typically a discrete change, or by assuming risk from given insureds for a longer period of time, which would be a continuous change.

Assume that the company holds total assets equal to $l_{1}+\cdots+l_{n}+k$, so in a very simplistic sense, $k$ is the capital or surplus of the company.

Next, define the probability of insolvency function and the expected policyholder deficit function for a single line $i$ as

$$
I_{i}\left(l_{i}, k\right)=\operatorname{Pr}\left(L_{i}>l_{i}+k\right)=1-F_{i}\left(l_{i}+k\right)
$$

and

$$
D_{i}\left(l_{i}, k\right)=\int_{l_{i}+k}^{\infty} t-\left(l_{i}+k\right) d F_{i}(t) .
$$

In both of these equations $l_{i}$ is performing double duty. It is the mean of $L_{i}$ and in $l_{i}+k$ it determines where $F_{i}$ is evaluated. To emphasize this we could write

$$
I_{i}\left(l_{i}, k\right)=1-F_{i}\left(l_{i}+k ; l_{i}\right) .
$$

Similar remarks hold for $D_{i} . D_{i}$ is not the expected policyholder deficit for line $i$ within a multiline company, rather it is the expected policyholder deficit for a monoline company which only writes line $i$.

Finally, let $F$ be the multivariate distribution of $\left(L_{1}\left(l_{1}\right), \ldots, L_{n}\left(l_{n}\right)\right)$, let $L=$ $L_{1}+\cdots+L_{n}$ be the total losses and let $F_{s}$ be the distribution function of $L$. Both $F$ and $F_{s}$ depend on $\left(l_{1}, \ldots, l_{n}\right)$. Define insolvency and expected deficit functions for the whole company by

$$
I\left(l_{1}, \ldots, l_{n}, k\right)=\operatorname{Pr}\left(\sum L_{i}>k+\sum l_{i}\right)=1-F_{s}\left(l_{1}+\cdots+l_{n}+k\right)
$$

and

$$
\begin{equation*}
D\left(l_{1}, \ldots, l_{n}, k\right)=\int_{\sum t_{i}>k+\sum l_{i}} \cdots \int_{1}+\cdots+t_{n}-\left(l_{1}+\cdots+l_{n}+k\right) d F\left(t_{1}, \ldots, t_{n}\right) \tag{2}
\end{equation*}
$$

With this notation $D_{i}\left(l_{i}, k\right)=D\left(0, \ldots, l_{i}, 0, \ldots, 0, k\right)$.
We focus on families of random variables $L(l)$ because in order to compute expressions like $\partial I / \partial l$ we need to know how the distribution $L(l)$ changes shape with changes in $l$. We need to work with $L(l+\epsilon)$ as well as $L(l)$ because

$$
\begin{aligned}
\frac{\partial I}{\partial l}= & -\frac{d}{d l} F(l+k ; l) \\
= & -\lim _{\epsilon \rightarrow 0} \frac{F(l+k+\epsilon ; l)-F(l+k ; l)}{\epsilon} \\
& \quad-\lim _{\epsilon \rightarrow 0} \frac{F(l+k ; l+\epsilon)-F(l+k ; l)}{\epsilon} .
\end{aligned}
$$

The partial derivative has a static part, where the mean of the underlying variable does not change, and a dynamic part, where the point of evaluation is fixed but the mean changes. This shows computing partial derivatives such as $\partial I / \partial l$ is inextricably linked to families of random variables.

## 3 Homogeneous Distributions and Homogeneous Prices

Myers and Read make one distributional assumption in their work, which we call homogeneity. In this section we explain how homogeneity is a natural assumption to make for assets but not for a portfolio of insurance risks. We also show that it is possible to construct arbitrage free homogeneous pricing functionals on inhomogeneous outcome distributions.

Consider two portfolios, one consisting of stock in a given company and the other consisting of insurance policies written on identical risks. Assume that the price of the stock is 1 today and let $X(n)$ be the price of a portfolio of $n$ of these stocks one year from now. If $S$ is the price distribution of the stock one year from now, then the value of the portfolio $X(n)$ has the same distribution as $n S$. More generally, returns from an investment advisor are likely to be similarly homogeneous; as the advisor gets more funds to invest he will increase his holdings in existing positions, and not suddenly start to invest in different asset classes.

Next, assume that the expected losses from each insurance policy in the portfolio has a present value of 1 today. Let $L(n)$ be the present value of total losses from a portfolio of $n$ policies. If $R$ is the distribution of losses from one policy, with $\mathrm{E}(R)=1$, then the distribution of $L(n)$ is the same as the distribution of $R_{1}+\cdots+R_{n}$, but it is not the same as $n R$, unless the $R_{i}$ are perfectly correlated. Since diversification is the basis for insurance, we will assume that the $R_{i}$ are identically distributed, but not perfectly correlated. Realistically, the $R_{i}$ will likely be somewhat correlated.

These two examples highlight an important difference between portfolios of investment-type risks and insurance-type risks. For a stock or other financial asset the meaning of $2 X$ is clear; we own two identical, equivalent and interchangeable stocks with the same price distribution now and at all future times. In contrast, for insurance risks, regulations regarding insurable interest and over-insurance make an interpretation as a policy which pays $\$ 2$ for each dollar loss unrealistic. In insurance, when we double expected losses we write twice as many policies and get a distribution $R_{1}+R_{2}$, with $R_{i}$ identically distributed, but less than perfectly correlated. A car can only have one driver; it is physically impossible to have two auto policies with perfectly correlated experience! Two auto policies, even if they have identical loss distributions, are subject to different random outcomes and together they are equivalent to a portfolio of stock in two different companies, not two stocks in one company.

The distinction between these two types of behaviour is crucial to the points we are making in this paper. To make the concept precise here is a formal definition.

Definition 1 A family of random variables $L(l)$ with $E(L(l))$ proportional to $l$ is called homogeneous in distribution, or simply homogeneous, if there exists a single random variable $U$ so that $L(l)$ has the same distribution as $l U$ for all $l$. Families which are not homogeneous are called inhomogeneous.

The requirement that $U$ is independent of $l$ is important since any random variable can be written as $L=E(L)(L / E(L))$. The future value of multiples of a given stock is clearly homogeneous in distribution. On the other hand, the present value of losses in a portfolio of identically distributed insurance policies is not homogeneous. An exponential variable $L$ with mean $l$ is a parametric homogeneous family, since $L=l U$ where $U$ has an exponential distribution with mean 1 . A normal variable with mean $l$ and standard deviation 1 is not homogeneous.

Homogeneity is Myers and Read's only distributional assumption. For it to hold in the way they assume, companies would have to quota share a portion of the entire market in a line, which Butsic (1999) calls a representative insurer approach. There is no major line of US property casualty insurance which operates in this way; it is an unrealistic assumption.

We now turn to the homogeneity of prices. The Fundamental Theorem of Asset Pricing states that the absence of arbitrage in a pricing system is equivalent to the existence of a positive linear pricing rule, see Dybvig and Ross (1989). A pricing rule is a function $q$ which assigns a price $q(X)$ to a random payoff $X$. The function $q$ is linear if for two random payoffs $X$ and $Y$ we have

$$
q(a X+b Y)=a q(X)+b q(Y)
$$

for all constants $a$ and $b$. If $q(a X)=a q(X)$ then $q$ is called homogeneous. Homogeneity is a necessary condition for $q$ to be arbitrage free. It is obvious that a sufficiently liquid market cannot be arbitrage free if the pricing functional is not homogeneous.

If $X(x)$ is a homogeneous family of random variables and $q$ is a homogeneous pricing rule then $q(X(x))=q(x X(1))=x q(X(1))$. If the family is not homogeneous then we need more assumptions in order to make similar statements. If $L(l)$ is an inhomogeneous family of random variables, but it is additive in the sense that $L(l+m)=L(l)+L(m)$, then if $q$ is linear we have $q(L(l+m))=q(L(l)+L(m))=q(L(l))+q(L(m))$. From this it follows by continuity that $q(L(l))=l q(L(1))$ and we recover a homogeneous pricing rule. In the insurance context, where $L(l)$ is typically modeled as a compound Poisson process or a mixed compound Poisson process, we have additivity (in fact, infinite divisibility). Thus it is possible for an inhomogeneous family to have a homogeneous and arbitrage free pricing rule.

Several specific examples of arbitrage free pricing functionals for inhomogeneous insurance distributions have been given in the literature. The first was the fundamental paper of Delbaen and Haezendonck (1989) which was then extended by Meister (1995). The key results are also reviewed in Embrechts and Meister (1995). Delbaen and Haezendonck show that if there are sufficiently many reinsurance markets then linear pricing functionals transform compound Poisson distributions to compound Poissons distributions. They then characterize the measures equivalent to a given compound Poisson which are themselves compound Poisson and show these are characterized via a separate adjustment of the frequency and severity. Specifically they show that an aggregate distribution $L_{t}=R_{1}+\cdots+R_{N(t)}$, with $R_{i}$ independent and identically distributed and $N(t)$ Poisson with mean $\lambda t$ transforms to a compound Poisson of the form
$\tilde{R}_{t}=\tilde{R}_{1}+\cdots+\tilde{R}_{\tilde{N}(t)}$ where $\tilde{N}(t)$ is Poisson with mean $\lambda^{\prime} t$ and the RadonNikodym derivative of $\tilde{R}$ with respect to $R$ is given by

$$
\frac{d \tilde{R}}{d R}=\exp (\beta(x)) / \mathrm{E}_{R}(\exp (\beta(R)))
$$

for some increasing function $\beta$. The transformed distribution can be regarded as risk-adjusted and prices can be computed as (linear) expected values with respect to the risk-adjusted probabilities, just as pricing is done on the asset side. Meister extends Delbaen and Haezendonck to mixed compound Poisson distributions.

To conclude, in this section we have defined homogeneous families of random variables and have shown that non-homogeneous families can still be priced using an arbitrage-free positive linear pricing functional. The failure of the adds-up result for inhomogeneous distributions is caused by different assumptions about the shape of the loss distribution rather than the lack of an arbitrage free pricing functional.

## 4 Statement and Proof of Main Result

We can now state our main result. The result depends on two technical lemmas which are stated and proved in Appendix 1.

Proposition 1 The following are equivalent.

1. For each $i=1, \ldots, n, L_{i}\left(l_{i}\right)$ is a homogeneous family of random variables.
2. For each $i=1, \ldots, n$

$$
\begin{equation*}
l_{i} \frac{\partial I_{i}}{\partial l_{i}}+k \frac{\partial I_{i}}{\partial k}=0 . \tag{3}
\end{equation*}
$$

3. For each $i=1, \ldots, n$

$$
\begin{equation*}
l_{i} \frac{\partial D_{i}}{\partial l_{i}}+k \frac{\partial D_{i}}{\partial k}=D_{i} . \tag{4}
\end{equation*}
$$

4. We have equality

$$
\begin{equation*}
l_{1} \frac{\partial I}{\partial l_{1}}+\cdots+l_{n} \frac{\partial I}{\partial l_{n}}+k \frac{\partial I}{\partial k}=0 . \tag{5}
\end{equation*}
$$

## 5. We have equality

$$
\begin{equation*}
l_{1} \frac{\partial D}{\partial l_{1}}+\cdots+l_{n} \frac{\partial D}{\partial l_{n}}+k \frac{\partial D}{\partial k}=D . \tag{6}
\end{equation*}
$$

The proposition says that each of the five statements holds if and only if all the other four hold. Put another way, if one of the five fails to hold then the other four will also fail. This means we can construct simple one line examples and can use items 2 and 3 generalize to the multi-line case, which simplifies the mathematics of the examples.

Proof We shall prove (4) implies (2) implies (1) implies (4), and then (5) implies (3) implies (1) implies (5), which is enough to show all the statements are equivalent.
(4) implies (2): Set $l_{j}=0$ for $j \neq i$ in Equation (5) to get Equation (3). This can also be seen geometrically using Lemma 1 which says $I$ is constant along rays from the origin. Therefore $I_{i}$, which is a restriction of $I$, is also constant along such rays.
(2) implies (1): Lemma 1 applied to $I_{i}$ shows there exists a function $\tilde{I}_{i}$ so that

$$
I_{i}\left(l_{i}, k\right)=\tilde{I}_{i}\left(k / l_{i}\right) .
$$

Let $U_{i}=L_{i} / l_{i}$, then $\operatorname{Pr}\left(U_{i}>u\right)=\tilde{I}_{i}(u-1)$ is independent of $l_{i}$ as required.
(1) implies (4): Assumption (1) implies that $I$ is constant along rays from the origin, so the result follows from Lemma 1.
(5) implies (3): Set $l_{j}=0$ for $j \neq i$ in Equation (6) to get Equation (4).
(3) implies (1): Let $U_{i}=L_{i} / l_{i}$. We have to show $\operatorname{Pr}\left(U_{i}>u\right)$ is independent of $l_{i}$. Let $l^{+}=\max (l, 0)$. Then, notice that

$$
\begin{align*}
\frac{\partial D}{\partial k} & =\frac{\partial}{\partial k} E\left[\left(l_{i} U_{i}-\left(l_{i}+k\right)\right)^{+}\right] \\
& =E\left[\frac{\partial}{\partial k}\left(l_{i} U_{i}-\left(l_{i}+k\right)\right)^{+}\right] \\
& =E\left[-\mathbf{1}_{\left\{l_{i} U_{i}>l_{i}+k\right\}}\right] \\
& =-\operatorname{Pr}\left(l_{i} U_{i}>l_{i}+k\right) \tag{7}
\end{align*}
$$

is minus the probability of default. Next, use Lemma 2 to define $\tilde{D}_{i}$ so that $D_{i}\left(l_{i}, k\right)=l_{i} \tilde{D}_{i}\left(k / l_{i}\right)$. Therefore

$$
\frac{\partial D_{i}}{\partial k}=\tilde{D}_{i}^{\prime}\left(k / l_{i}\right)
$$

and so

$$
\operatorname{Pr}\left(U_{i}>u\right)=-\tilde{D}_{i}^{\prime}(u-1)
$$

is independent of $l_{i}$ as required.
(1) implies (5): Assumption (1) shows we can write $D$ as

$$
D\left(l_{1}, \ldots, l_{n}, k\right)=k \tilde{D}\left(l_{1} / k, \ldots, l_{n} / k\right)
$$

so the result follows from Lemma 2.

The results in Proposition 1 are clearly similar to Myers and Read's results but they are not exactly the same. We shall now explain how to derive their exact result. For simplicity we shall assume $n=2$ and work with just $l_{1}$ and $l_{2}$ in the rest of the section.

Myers and Read's "adds-up" result (their Equation A1-3) involves computing the marginal increase in surplus required to hold the default value constant, given a marginal increase in a particular line. We have been taking a slightly different approach: if we hold the surplus and default value constant, what decrease is needed in line 2 to offset an increase in line 1 ? However, it is easy to reconcile the two approaches. To do this, let $s_{1}$ and $s_{2}$ be the marginal surplus requirements for each line. Note that $s_{1}$ and $s_{2}$ are ratios whereas $k$ is a dollar amount. Myers and Read then use a capital amount $k=s_{1} l+s_{2} l_{2}$ and define the default value $D_{M}$ (to distinguish from our $D$ ) as

$$
D_{M}\left(l_{1}, l_{2}\right):=D\left(l_{1}, l_{2}, s_{1} l_{1}+s_{2} l_{2}\right) .
$$

Myers and Read use the following notation in their Appendix 1. They write $\tilde{L}_{a}=L_{a} \tilde{R}_{a}$, where $L_{a}$ corresponds to our $l_{1}, \tilde{R}_{a}$ to $U_{1}$ and $\tilde{L}_{a}$ to $L_{1}$. Thus $\tilde{L_{a}}=L_{a} \tilde{R}_{a}$ translates into our $L_{1}=l_{1} U_{1}$, i.e. the homogeneity assumption. The value $L_{a}$ is the expected value of $\tilde{L}_{a}$ at time 0 . We are ignoring the time value of money here by assuming an interest rate of zero. Myers and Read also work with a fixed interest rate and then integrate over all possible rates-an extra level of sophistication that need not concern us.

We can now prove their result. In fact, Proposition 1 shows the "adds-up" result holds if and only if the families $L_{i}$ are homogeneous.

Corollary 1 (Myers and Read) Assume losses $L_{i}$ form a homogeneous family for each i. Then default values "add-up" in that

$$
l_{1} \frac{\partial D_{M}}{\partial l_{1}}+l_{2} \frac{\partial D_{M}}{\partial l_{2}}=D_{M} .
$$

Proof Computing using the chain-rule and then applying Proposition 1 item 5 in Equation (8) gives:

$$
\begin{align*}
l_{1} \frac{\partial D_{M}}{\partial l_{1}}+l_{2} \frac{\partial D_{M}}{\partial l_{2}} & =l_{1}\left(\frac{\partial D}{\partial l_{1}}+s_{1} \frac{\partial D}{\partial k}\right)+l_{2}\left(\frac{\partial D}{\partial l_{2}}+s_{2} \frac{\partial D}{\partial k}\right) \\
& =l_{1} \frac{\partial D}{\partial l_{1}}+l_{2} \frac{\partial D}{\partial l_{2}}+\left(s_{1} l_{1}+s_{2} l_{2}\right) \frac{\partial D}{\partial k} \\
& =D\left(l_{1}, l_{2}, s_{1} l+s_{2} l_{2}\right)  \tag{8}\\
& =D_{M}\left(l_{1}, l_{2}\right)
\end{align*}
$$

as required.
Simple Proof Here is the simple, self-contained proof we promised in the introduction. Dividing through by $l_{1}$ in the definition of $D$, Equation (2), it is clear that $D_{M}\left(l_{1}, l_{2}\right)=l_{1} \tilde{D}_{M}\left(l_{2} / l_{1}\right)$ for some function $\tilde{D}_{M}$. Thus

$$
\begin{aligned}
l_{1} \frac{\partial D_{M}}{\partial l_{1}}+l_{2} \frac{\partial D_{M}}{\partial l_{2}} & =l_{1}\left(\tilde{D}_{M}-\frac{l_{2}}{l_{1}} \frac{\partial D_{M}}{\partial l_{1}}\right)+l_{2} \frac{\partial D_{M}}{\partial l_{2}} \\
& =D_{M}
\end{aligned}
$$

which completes the proof.

## 5 Examples

### 5.1 Examples of Homogeneity

Homogeneous families can be made from a wide variety of continuous distributions. For example, varying the scale parameter $\theta$ and holding all other parameters constant for any of the distributions listed in Appendix A of Klugman, Panjer and Willmot (1998), which have a scale parameter $\theta$, will produce a homogeneous family. This includes suitable parameterizations of the transformed beta, Burr, generalized Pareto, Pareto, transformed gamma, gamma, Weibull, exponential, and inverse Gaussian. By Proposition 1, sums of selected from such families will also be homogeneous. Also, trivially, if $U$ is any distribution with mean 1 then $l U$ is a homogeneous family as $l$ varies.

### 5.2 Examples of Inhomogeneity

It is easy to construct examples where the homogeneity assumption fails. All members of a homogeneous family have the same coefficient of variation, therefore a family with a non-constant coefficient of variation will not be homogeneous. For example, let $L$ be normally distributed with mean $l$ and constant standard deviation 1. Then $L$ is not homogeneous. By definition $I(l, k)=1-\Phi(k)$ so

$$
l \frac{\partial I}{\partial l}+k \frac{\partial I}{\partial k}=-k \phi(k) \neq 0
$$

where $\Phi$ and $\phi$ are the distribution and density for the standard normal. Proposition 1 implies this expression equals zero if $L$ is homogeneous. If the reader
is skeptical about using only one variable, he or she will find it easy to construct multivariate distribution examples using normal variables.

It is less simple, but still possible, to construct examples where the coefficient of variation is a constant function of the mean, but which nevertheless fail to satisfy the homogeneity assumption. For example let $L(l)$ be distributed as a gamma random variable with parameters $\alpha=4 l^{2}, \theta=1 / 2$ shifted by $l(1-2 l)$. Here we are using the Klugman, Panjer, Willmot parameterization so $f(t ; \alpha, \theta)=$ $(t / \theta)^{\alpha} e^{-t / \theta} / t \Gamma(\alpha)$. It is easy to check $L(l)$ has mean $l$, constant coefficient of variation 1 and skewness $1 / l$, since the skewness of a gamma $\alpha, \theta$ is $2 / \sqrt{\alpha} . I$ is given by the incomplete gamma function, $I(l, k)=\Gamma\left(4 l^{2}, 4 l^{2}+2 k\right)$, which does not satisfy the assumptions of Lemma 1, so $L(l)$ is not homogeneous. The reason is clear: the family $L(l)$ changes shape with $l$ and so cannot be homogeneous. Taking this a step further, it is possible to construct a family all of whose higher cumulants (coefficient of variation, skewness, kurtosis, etc.) are independent of the mean, just as they would be for a homogeneous family, but which nevertheless fails to be homogeneous.

### 5.3 Aggregate Distributions are Inhomogeneous

The central distributions of insurance, compound Poisson and mixed compound Poisson distributions are inhomogeneous, because the coefficient of variation depends on the mean.

Let $L=R_{1}+\cdots R_{N}$ where the $R_{i}$ are independent, identically distributed severities and $N$ is a frequency distribution with mean $n$. Increasing expected
losses in this model involves increasing $n$. Suppose $N$ has contagion $c$, so, as suggested by Heckman and Meyers $(1983), \operatorname{Var}(N)=n(1+c n)$. Then

$$
\mathrm{CV}(L)^{2}=\frac{\mathrm{CV}(R)^{2}}{n}+\frac{1}{n}+c
$$

is clearly not independent of $n$. Thus $L$ does not satisfy the homogeneity assumption: the aggregate loss distribution changes shape as $n$ increases. This is illustrated in the figure below, which shows six aggregate loss distributions with the same severity distribution but different claim counts, indicated by " $\mathrm{CC}=20$ " for $n=20$, and so forth. The individual densities have been scaled so that if the family were homogeneous then all the densities would be identical and only one line would appear in the plot.

If aggregate distributions can be approximated by various families of parametric distributions, and if those families are homogeneous, does this result really matter? The answer is an emphatic "yes". The above example shows that in the real world, where insurers grow by adding discrete insureds, the "adds-up" results do not hold because the way the aggregate distribution changes shape forces parameters other than the scale parameter to change as the mean increases, and thus homogeneity is lost.


## 6 Inhomogeneity is Material

In this section we will discuss how the Myers Read formula is likely to be applied in practice, and what we would intuitively expect the formula to show for an insurance portfolio. Then we will extend the examples given in the original paper to allow for inhomogeneity. The extended examples show that the inhomogeneity inherent in a typical portfolio of property casualty risks is large enough to invalidate the Myers and Read allocation formula.

### 6.1 Use of the Myers and Read allocation in pricing

Myers and Read's paper tries to explain how capital should be allocated across a company's different lines of business. They point out that "because surplus is costly, competitive premiums...depend on total surplus requirements and on their
allocation to lines of insurance." They are expecting capital allocation to be used in the context of measuring profitability and setting targets for divisions or lines within a company. Internal company specific allocations are irrelevant to determining market prices. Knowing how the formula will be applied helps calibrate the scale for our examples of inhomogeneity. Clearly the relevant scale is much smaller than the whole industry; only $7.5 \%$ of US property casualty company groups had total gross premium greater than $\$ 1 \mathrm{~B}$ in 2002, whereas over $84 \%$ had total gross premium less than $\$ 300 \mathrm{M}$. An allocation of capital within a company will likely be on a scale of $\$ 10-100 \mathrm{M}$. We will give examples to show that inhomogeneity is very material at this scale.

### 6.2 Heuristics

Let $L(l)$ be a smooth family of random variables with $\mathrm{E}(L(l))=l$. Let $F(t, l)=$ $\operatorname{Pr}(L(l)<t)$ be the distribution function of $L(l)$ and $f(t, l)=\partial F / \partial t$ be its density. The expected default value, with capital ratio $s$, is defined as

$$
D(l)=\int_{l(1+s)}^{\infty}(t-l(1+s)) f(t, l) d t
$$

Note that $l(1+s)$ represents total assets: $l$ from the loss and $l s$ from capital. In a more sophisticated model we could consider profit in the premium; here we simply subsume it into the constant $s$.

By Proposition 1 we know

$$
l \frac{\partial D}{\partial l}=D
$$

if and only if $L(l)$ is a homogeneous family, which is then equivalent to the MyersRead adds-up result.

A homogeneous family offers no diversification benefit as the mean increases. Property casualty insurance is based on diversification, and the resulting inhomogeneity in a portfolio of insurance risks means that the relative riskiness of the portfolio decreases as expected losses increase. Since a lower risk portfolio has a lower expected default, one would expect that

$$
\begin{equation*}
l \frac{\partial D}{\partial l}<D \tag{9}
\end{equation*}
$$

for an inhomogeneous insurance portfolio. Instead of "adds-up" we expect to see a "sub-adds-up" result for inhomogeneous distributions which exhibit decreasing coefficient of variation with expected losses, such as aggregate distributions.

Meyers, Klinker and Lalonde (2003) introduce the heterogeneity multiplier, which is a constant $\lambda$ defined so that

$$
\lambda l \frac{\partial D}{\partial l}=D .
$$

They shows that $\lambda$ is typically greater than 1 (as expected) and find a value close to 1.6 in some empirical examples.

If $L$ is homogeneous then, for all marginal capital ratios $s>0$,

$$
l \frac{\partial D}{\partial l}=D \geq 0
$$

However, intuitively, one would expect that for a large enough capital ratio $s$ it should be possible for the extra capital associated with writing more business to more than offset the extra risk. This would imply that

$$
l \frac{\partial D}{\partial l}<0
$$

should be possible for sufficiently large $s$. This is another difference between homogeneous and inhomogeneous families.

### 6.3 Extended Myers Read Examples

We now extend the examples given in Myers Read to show the impact of inhomogeneity on the adds-up result. We will focus on the lognormal examples given in Table 2 (page 560) of the original paper and will follow the same notation as far as possible. There are three lines of insurance $L_{i}, i=1,2,3$ with expected losses $\mathrm{E}\left(L_{i}\right)=l_{i}$. Let $l=\sum l_{i}$ and let $x_{i}=l_{i} / l$ be the proportion of losses from line $i$. Let $\rho_{i j}$ be the correlation between $\log \left(L_{i}\right)$ and $\log \left(L_{j}\right)$. As Myers and Read point out, if the line-by-line loss volatilities are not large then the volatility of total losses is closely approximated by

$$
\sigma_{L}^{2}=\sum_{i} \sum_{j} x_{i} x_{j} \rho_{i j} \sigma_{i} \sigma_{j}
$$

where $\sigma_{i}$ is the volatility (coefficient of variation) of line $i$. If $\sigma_{V}$ is the volatility of assets $V$ then the correlation between log loss and log assets is approximately

$$
\sigma_{L V}=\sum_{i} x_{i} \rho_{i V} \sigma_{i} \sigma_{V}
$$

where $\rho_{i V}$ is the correlation between $\log$ assets and $\log$ line $i$ losses. Lastly, let $s_{i}$ be the marginal level of capital for line $i$ per dollar of losses and let $s=\sum_{i} x_{i} s_{i}$ be the weighted average capital ratio.

Let $D$ be the value of the default option, $d=D / l$ and

$$
d_{i}=\frac{\partial D}{\partial l_{i}}
$$

An easy computation shows

$$
d_{i}=d+\frac{\partial d}{\partial x_{i}}
$$

Myers and Read Appendix 2 shows that

$$
\begin{equation*}
d=N(z)-(1+s) N(z-\sigma) \tag{10}
\end{equation*}
$$

where

$$
z=\frac{-\log (1+s)+\sigma^{2} / 2}{\sigma}
$$

and

$$
\begin{equation*}
\sigma^{2}=\sigma_{L}^{2}+\sigma_{V}^{2}-2 \sigma_{L V} \tag{11}
\end{equation*}
$$

They also compute

$$
\frac{\partial d}{\partial x_{i}}=\frac{\partial d}{\partial s} \frac{\partial s}{\partial x_{i}}+\frac{\partial d}{\partial \sigma} \frac{\partial \sigma}{\partial x_{i}} .
$$

Both $\partial d / \partial s$ and $\partial d / \partial \sigma$ can be computed from Equation (10). Next, since $l_{i}=x_{i} l$

$$
\frac{\partial s}{\partial x_{i}}=\frac{\partial s}{\partial l_{i}} \frac{\partial l_{i}}{\partial x_{i}}=\left(-\frac{1}{l^{2}} \sum_{i} l_{i} s_{i}+\frac{s_{i}}{l}\right) l=-s+s_{i} .
$$

Finally, Myers and Read compute $\partial \sigma / \partial x_{i}$ by noting

$$
\frac{\partial \sigma}{\partial x_{i}}=\frac{\partial \sigma}{\partial l_{i}} \frac{\partial l_{i}}{\partial x_{i}}=l \frac{\partial \sigma}{\partial l_{i}},
$$

and then differentiating Equation (11) with respect to $l_{i}$ to get

$$
\begin{align*}
\sigma \frac{\partial \sigma}{\partial l_{i}}= & \sigma_{L} \frac{\partial \sigma_{L}}{\partial l_{i}}-\frac{\partial \sigma_{L V}}{\partial l_{i}} \\
= & \sum_{k} \frac{l_{k}}{l^{2}} \rho_{i k} \sigma_{k} \sigma_{i}-\frac{1}{l} \sum_{j k} \frac{l_{j} l_{k}}{l^{2}} \rho_{i j} \sigma_{j} \sigma_{k} \\
& -\left(\frac{\rho_{i V} \sigma_{i} \sigma_{V}}{l}-\sum_{j} \frac{l_{j}}{l^{2}} \rho_{i V} \sigma_{i} \sigma_{V}\right) \\
& =\left(\sigma_{i L}-\sigma_{L}^{2}-\left(\sigma_{i V}-\sigma_{L V}\right)\right) / l \tag{12}
\end{align*}
$$

Here the first term in the middle line defines $\sigma_{i L}$ and the last two terms define $\sigma_{i V}$ and $\sigma_{L V}$ respectively. This derivation has used the fact that $\partial \sigma_{i} / \partial l_{i}=0$ for each $i$. Combining these equations gives

$$
\begin{equation*}
d_{i}=d+\frac{\partial d}{\partial s}\left(s_{i}-s\right)+\frac{\partial d}{\partial \sigma} \frac{1}{\sigma}\left(\left(\sigma_{i L}-\sigma_{L}^{2}\right)-\left(\sigma_{i V}-\sigma_{L V}\right)\right) . \tag{13}
\end{equation*}
$$

We have now defined all the expressions needed to understand Myers and Read's Table 2, which is reproduced here in Tables 1, 2 and 3.

Table 1: Base Case Parameters

| Item | Amt | $x_{i}$ | $\sigma$ | Correlations |  |  | Cov / L | Cov / V |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | Line 1 | Line 2 | Line 3 |  |  |
| Line 1 | 100 | 33.3\% | 10.00\% | 1.000 | 0.500 | 0.500 | 0.0092 | -0.0030 |
| Line 2 | 100 | 33.3\% | 15.00\% | 0.500 | 1.000 | 0.500 | 0.0150 | -0.0045 |
| Line 3 | 100 | 33.3\% | 20.00\% | 0.500 | 0.500 | 1.000 | 0.0217 | -0.0060 |
| Liab $L$ | 300 | 100.0\% | 12.36\% | 0.742 | 0.809 | 0.876 | 0.0153 | -0.0045 |
| Assets | 450 | 150.0\% | 15.00\% | -0.200 | -0.200 | -0.200 |  | 0.0225 |
| Surplus | 150 | 50.0\% |  |  |  |  |  |  |

Table 2: Base Case $\sigma$ and $d$

| $\sigma$ | $21.62817 \%$ |
| :--- | :---: |
| $d$ | $0.311220 \%$ |
| Delta | -0.0237 |
| Vega | 0.0838 |

Table 1 summarizes the input parameters. Table 2 shows the resulting values for $\sigma$ and $d$. The entries in Table 3 are determined using Equation (13) by setting $s_{i}=s$ and solving for $d_{i}$ in the first column and setting $d_{i}=d$ and solving for $s_{i}$ in the second. Weighting the individual line values by $x_{i}$ recovers the adds-up result; the total in the first column is exactly $d$ and in the second is exactly $s$.

Table 3: Homogeneous Case: "Adds-up" Holds

| Line | Def Val/Liab | Surp / Liab |
| :--- | :---: | :---: |
| Line 1 | $0.016 \%$ | $37.55 \%$ |
| Line 2 | $0.300 \%$ | $49.55 \%$ |
| Line 3 | $0.617 \%$ | $62.90 \%$ |
| Total | $0.311 \%$ | $50.00 \%$ |

In an inhomogeneous family the volatility varies with expected losses, so $\sigma_{i}=$ $\sigma_{i}\left(l_{i}\right)$, and we need to add $\partial \sigma_{i} / \partial l_{i}$ terms to Equation (12). The additional terms are

$$
\sum_{j} \frac{l_{i} l_{j}}{l^{2}} \rho_{i j} \sigma_{j} \frac{\partial \sigma_{i}}{\partial l_{i}}-\frac{l_{i}}{l} \rho_{i V} \sigma_{V} \frac{\partial \sigma_{i}}{\partial l_{i}} .
$$

Combining these terms with Equation (13) we get the following equation for $d_{i}$

$$
\begin{align*}
d_{i}= & d+\frac{\partial d}{\partial s}\left(s_{i}-s\right)+\frac{\partial d}{\partial \sigma} \frac{1}{\sigma}\left(\left(\sigma_{i L}-\sigma_{L}^{2}\right)-\left(\sigma_{i V}-\sigma_{L V}\right)\right) \\
& +\frac{\partial d}{\partial \sigma} \frac{\partial \sigma_{i}}{\partial l_{i}} \frac{1}{\sigma}\left(\sum_{j} \frac{l_{i} l_{j}}{l} \rho_{i j} \sigma_{j}-l_{i} \rho_{i V} \sigma_{V}\right) . \tag{14}
\end{align*}
$$

We now have to determine how $\sigma_{i}$ is likely to vary with $l_{i}$ in a real world portfolio. To do this, we look at a realistic aggregate loss distribution in order to determine $\sigma_{i}\left(l_{i}\right)$ and then to approximate the actual distributions with a family of lognormals. If we use a compound Poisson model where $L=R_{1}+\cdots+R_{N}, N$ Poisson with mean $n$ then the volatility (coefficient of variation) of $L$ is

$$
\sigma(l)=\sqrt{\frac{x\left(\gamma^{2}+1\right)}{l}}
$$

where $x=\mathrm{E}(R)$ is severity, $\gamma$ is the coefficient of variation of $R$, and $l=\mathrm{E}(L)=$ $n x$. Hence

$$
\frac{\partial \sigma}{\partial l}=-\frac{1}{2} \sqrt{\frac{x\left(\gamma^{2}+1\right)}{l^{3}}} .
$$

More generally, if $N$ is a negative binomial (gamma mixture of Poisson frequencies) with $\operatorname{Var}(N)=n(1+c n)$ then the volatility of $L$ is

$$
\sigma(l)=\sqrt{\frac{x\left(\gamma^{2}+1\right)}{l}+c}
$$

and so

$$
\frac{\partial \sigma}{\partial l}=-\frac{x\left(\gamma^{2}+1\right)}{2 l^{2} \sigma(l)} .
$$

Before presenting examples with inhomogeneous losses we have to determine reasonable values for $x$ and $\gamma$. Since the examples use expected losses of 100, the expected claim count for each line will be $100 / x$. We consider three cases. The first example calibrates expected claim counts to correspond to a book of approximately $\$ 300 \mathrm{M}$ casualty business with an average severity of $\$ 4,688$ per claim. This is a scale appropriate to a large division or whole medium sized company. The second example uses a similar overall scale but a higher severity and hence greater inhomogeneity. The third example calibrates to a $\$ 3 \mathrm{~B}$ total loss; this corresponds to the largest of companies and we expect the effect of inhomogeneity to be less material. Only $3 \%$ of US property casualty companies have one or more lines with more than $\$ 1 \mathrm{~B}$ of gross premium.

In all three examples $x$ and $\gamma$ are chosen to approximate a real line of business and then $c$ is determined so that the volatility of each line is the same as shown in Table 1. This means the values of $d$, Delta and Vega are as shown in Table 2 in all three cases, because these quantities do not depend on $\partial \sigma_{i} / \partial l_{i}$. Only $d_{i}$ and $s_{i}$ which are shown in Table 3 vary between the examples. The values for the first example are shown in Table 4 . Line 1 roughly corresponds to $\$ 100 \mathrm{M}$
expected loss for workers compensation. It has an average of 50,000 claims, each with average severity $\$ 2,000$ and severity volatility of 20 . Line 2 corresponds to a book of general liability policies with $\$ 1 \mathrm{M}$ limits, and Line 3 approximates a book of medium sized property risks. The contagion values $c$ have been chosen so that the implied line volatilities are as shown in Table 1, viz. $0.10,0.15$, and 0.2 . (These volatilities are lower than one would expect to see in real portfolios, but are used to facilitate comparison with the original paper.) The by-line defaults are shown under "Default Value"; the weighted average default is $0.1667 \%$ less than half $d=0.311 \%$. The last column shows the individual line surplus allocations; again, the weighted average allocated capital is $43.9 \%$ less than the actual $50 \%$. This shows that we recover sub-additivity, as expected from Equation (9).

To gauge the magnitude of the differences between Table 3 and 4 on pricing, suppose the company desired a $10 \%$ return on allocated surplus from underwriting cash flows. Table 3 would give profit targets of $3.8 \%, 5.0 \%$ and $6.3 \%$ for lines 1, 2 and 3, whereas Table 4 would give $3.0 \%, 4.5 \%$ and $5.7 \%$. These differences are material relative to the inter-line differences. As we have already observed, the total target in Table 4 would fall short because of the failure of targets to add-up. The targets in Table 4 could be re-scaled, but that would introduce an arbitrary choice that the canonical Myers Read decomposition specifically sought to remove.

Table 5 also uses $\$ 100 \mathrm{M}$ expected losses by line, but increases the severities by line-thereby increasing the inhomogeneity. This type of book, while more extreme than the first example, is still a realistic example. The failure of the addsup theorem is more pronounced in this case, with the surplus allocation total being

Table 4: Average Severity Lines

| Line | $\mathrm{E}(N)$ | $x=\mathrm{E}(X)$ | $c$ | $\gamma$ | Default Value | Surplus |
| :--- | ---: | ---: | :---: | ---: | ---: | :---: |
| Line 1 | $50,000.0$ | $2,000.0$ | 0.002 | 20.000 | $-0.1727 \%$ | $29.5740 \%$ |
| Line 2 | $4,000.0$ | $25,000.0$ | 0.016 | 5.000 | $0.1913 \%$ | $44.9394 \%$ |
| Line 3 | $10,000.0$ | $10,000.0$ | 0.030 | 10.000 | $0.4815 \%$ | $57.1892 \%$ |
| Total | $64,000.0$ | $4,687.5$ |  |  | $0.1667 \%$ | $43.9008 \%$ |

Table 5: Higher Severity Lines

| Line | $\mathrm{E}(N)$ | $x=\mathrm{E}(X)$ | $c$ | $\gamma$ | Default Value | Surplus |
| :--- | ---: | ---: | ---: | ---: | ---: | :---: |
| Line 1 | $5,000.0$ | $20,000.0$ | 0.005 | 5.000 | $-0.1062 \%$ | $32.3795 \%$ |
| Line 2 | $2,000.0$ | $50,000.0$ | 0.010 | 5.000 | $0.0822 \%$ | $40.3330 \%$ |
| Line 3 | $10,000.0$ | $10,000.0$ | 0.004 | 19.000 | $0.1318 \%$ | $42.4277 \%$ |
| Total | $17,000.0$ | $17,647.1$ |  |  | $0.0359 \%$ | $38.3801 \%$ |

$24 \%$ lower than required. Line 1 is closer to homogeneous because $\gamma$ is lower; line 3 is less homogeneous because $\gamma$ is higher. These observations are reflected in the differences in surplus allocation.

Table 6 uses \$1B expected losses by line, generating over 3M claim counts. Here, the results are very close to homogeneous, as expected. The default value is $0.307 \%$, very close to the homogeneous $0.311 \%$, and the surplus total is $49.8 \%$ vs. $50 \%$. According to 2002 statutory annual statements, only $3 \%$ companies reported one or more line of business with more than \$1B gross earned premium. Thus such large company/lines are the exception, and to the extent Myers Read is used for internal capital allocation, the scale will generally be at or below that used in Tables 4 and 5.

Table 6: Large Company Example

| Line | $\mathrm{E}(N)$ | $x=\mathrm{E}(X)$ | $c$ | $\gamma$ | Def. Value | Surplus |
| :--- | :---: | ---: | :---: | :---: | ---: | :---: |
| Line 1 | $1,000,000.0$ | 1000.0 | 0.010 | 10.000 | $0.0139 \%$ | $37.4523 \%$ |
| Line 2 | $1,000,000.0$ | 1000.0 | 0.022 | 15.000 | $0.2967 \%$ | $49.3856 \%$ |
| Line 3 | $1,000,000.0$ | 1000.0 | 0.040 | 20.000 | $0.6115 \%$ | $62.6747 \%$ |
| Total | $3,000,000.0$ | 1000.0 |  |  | $0.3074 \%$ | $49.8375 \%$ |

## 7 Conclusions

In this paper we have explained the importance of the homogeneity assumption in the derivation of Myers and Read's "adds-up" result. Proposition 1 shows the assumption is necessary as well as sufficient. We have shown that aggregate loss distributions are not homogeneous, and given examples to show that the inhomogeneity in a realistically sized loss portfolio will cause the adds-up result to materially fail. Thus the Myers Read allocation formula is not the panacea it seemed and it will find little practical application in insurance companies. The methods introduced by Myers and Read can, however, be usefully applied to manage a company using constrained optimization, and maximizing return on marginal surplus. This is a more fruitful approach than trying to allocate capital, and it is discussed further in Meyers et al. (2003).

## Appendix 1: Two Technical Lemmas

Lemma 1 Let $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ be a differentiable function of $n$ variables. Then

$$
x_{1} \frac{\partial f}{\partial x_{1}}+x_{2} \frac{\partial f}{\partial x_{2}}+\cdots+x_{n} \frac{\partial f}{\partial x_{n}}=0
$$

if and only if $f$ is constant along rays from the origin.

Note: If $f$ is constant on lines through the origin then $f$ is called homogeneous. The lemma requires only that $f$ be constant along rays from the origin; along a line $f$ can change as the line passes through the origin. The function $x \mapsto x /|x|$ is a good example of what can occur: it changes value from +1 to -1 at zero. If $f$ is constant along rays from the origin, then in half spaces through the origin $f$ can be expressed as a function of $x_{i} / x_{j}, i=1, \ldots, n$ when $x_{j} \neq 0$, for each $j$. In our applications of this lemma, the domain of $f$ is the positive quadrant, and hence there is no difference between lines through the origin and rays from the origin in the domain. I would like to thank Christopher Monsour for pointing this out to me.

Proof Sufficiency: if $f$ is constant along rays through the origin, then by the note we can assume locally that $f\left(x_{1}, \ldots, x_{n}\right)=\tilde{f}\left(x_{1} / x_{n}, \ldots, x_{n-1} / x_{n}\right)$ for some function $\tilde{f}$ of $n-1$ variables. An easy calculation shows

$$
\begin{aligned}
x_{1} \frac{\partial f}{\partial x_{1}}+\cdots+x_{n} \frac{\partial f}{\partial x_{n}} & =\frac{x_{1}}{x_{n}} \tilde{f}_{1}+\cdots+\frac{x_{n-1}}{x_{n}} \tilde{f}_{n-1}-x_{n}\left(\frac{x_{1}}{x_{n}^{2}} \tilde{f}_{1}+\cdots+\frac{x_{n-1}}{x_{n}^{2}} \tilde{f}_{n-1}\right) \\
& =0
\end{aligned}
$$

where $\tilde{f}_{i}=\partial \tilde{f}\left(x_{1}, \ldots, x_{n-1}\right) / \partial x_{i}$.
Necessity: Let $\mathbf{v}=\left(x_{1}, \ldots, x_{n}\right)$ be a differentiable curve, so $\mathbf{v}=\mathbf{v}(t): \mathbb{R} \rightarrow$ $\mathbb{R}^{n}$, with $d \mathbf{v} / d t=\mathbf{v}$. This means $\mathbf{v}$ is equal to its own tangent vector for each $t$. By separating variables it is easy to see that $\mathbf{v}$ is a line through the origin. (It has the form $e^{t}\left(k_{1}, \ldots, k_{n}\right)$ for constants of integration $k_{i}$.) Then, by the chain-rule

$$
\begin{aligned}
\frac{d}{d t} f(\mathbf{v}(t)) & =x_{1} \frac{\partial f}{\partial x_{1}}+\cdots+x_{n} \frac{\partial f}{\partial x_{n}} \\
& =0
\end{aligned}
$$

by assumption, so the directional derivative of $f$ along each half of any such line $\mathbf{v}$ is constant, i.e. $f$ is constant along rays from the origin, as required. Since $\mathbf{v}$ never reaches the origin, we cannot assert that $f$ is constant along lines through the origin.

Lemma 2 Let $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ be a differentiable function of $n$ variables. Then,

$$
\begin{equation*}
x_{1} \frac{\partial f}{\partial x_{1}}+\cdots+x_{n} \frac{\partial f}{\partial x_{n}}=f \tag{15}
\end{equation*}
$$

on a half-space where $x_{1}>0\left(\right.$ resp. $\left.x_{1}<0\right)$ if and only if there exists a differentiable function $\tilde{f}$ so that $f\left(x_{1}, \ldots, x_{n}\right)=x_{1} \tilde{f}\left(x_{2} / x_{1}, \ldots, x_{n} / x_{1}\right)$ on that half space, and similarly for $x_{2}, \ldots, x_{n}$.

Proof If $f\left(x_{1}, \ldots, x_{n}\right)=x_{1} \tilde{f}\left(x_{2} / x_{1}, \ldots, x_{n} / x_{1}\right)$ then, using subscripts on $\tilde{f}$ to denote partial derivatives,

$$
\begin{aligned}
x_{1} \frac{\partial f}{\partial x_{1}}+\cdots+x_{n} \frac{\partial f}{\partial x_{n}} & =\left(x_{1} \tilde{f}-\sum_{j=2}^{n} x_{j} \tilde{f}_{j-1}\right)+\sum_{j=2}^{n} x_{j} \tilde{f}_{j-1} \\
& =f
\end{aligned}
$$

The first sum comes from the partial derivative with respect to $x_{1}$ and the second sum comes from all the remaining partials.

On the other hand, suppose $f$ satisfies Equation (15) and let $\tilde{f}\left(t, s_{2}, \ldots, s_{n}\right)=$ $f\left(t, s_{2} t, \ldots, s_{n} t\right) / t$ where $t>0$ (resp. $t<0$ ). We must show $\tilde{f}$ is independent of $t$. Differentiating

$$
\begin{aligned}
\frac{\partial}{\partial t}\left(\frac{f\left(t, s_{2} t, \ldots, s_{n} t\right)}{t}\right) & =-\frac{1}{t^{2}} f+\frac{1}{t}\left(\frac{\partial f}{\partial x_{1}}+\sum_{j=2}^{n} s_{j} \frac{\partial f}{\partial x_{j}}\right) \\
& =0
\end{aligned}
$$

and the result follows.

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